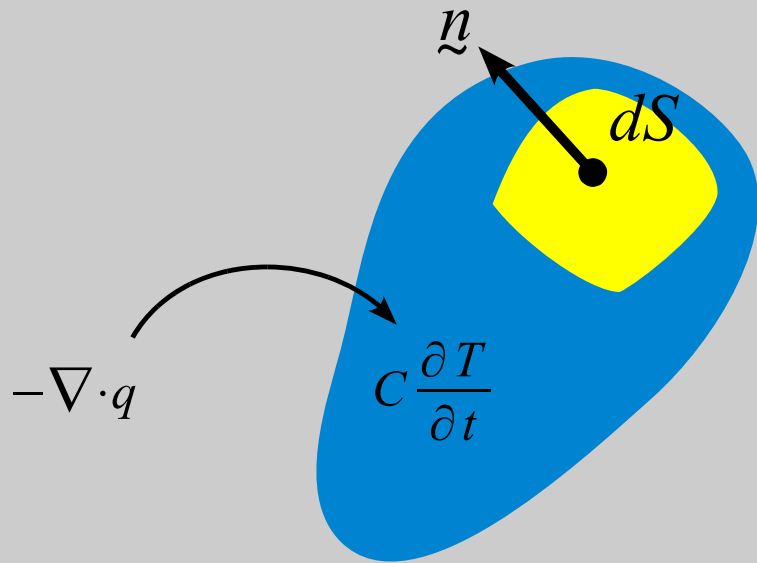


# 擴散方程式



$$\oint q \cdot n dS = \int \nabla \cdot q d v$$

$$-\int \nabla \cdot q d v = \int \rho c \frac{\partial T}{\partial t} d v$$

$$q = -k \nabla T \quad (\text{擴散定律})$$

$$\Rightarrow \int (k \nabla^2 T - \rho c \frac{\partial T}{\partial t}) d v = 0$$

$$\Rightarrow \frac{\partial T}{\partial t} = \frac{k}{\rho c} \nabla^2 T$$

# 分離變數法

$$\nabla^2 T = \frac{1}{\alpha^2} \frac{\partial T}{\partial t}$$

$$u \equiv \Psi(r) T(t)$$

$$\Rightarrow \frac{1}{\Psi} \nabla^2 \Psi = \frac{1}{\alpha^2} T \frac{dT}{dt} = -\lambda^2$$

$$\Rightarrow \begin{cases} \frac{dT}{dt} + (\lambda \alpha)^2 T = 0 \longrightarrow T = e^{-(\lambda \alpha)^2 t} \\ (\nabla^2 + \lambda^2) \Psi \equiv 0 \end{cases}$$

# 正交函數展開法

# 卡氏座標系

$$\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} + \frac{\partial^2 \Psi}{\partial z^2} + \lambda^2 \Psi = 0$$

$$\Psi \equiv R(r) \Theta(\theta) \Phi(\phi)$$

$$\Rightarrow \frac{1}{X} \frac{d^2 X}{dx^2} + \frac{1}{Y} \frac{d^2 Y}{dy^2} + \frac{1}{Z} \frac{d^2 Z}{dz^2} + \lambda^2 = 0$$

$$\frac{1}{Z} \frac{d^2 Z}{dz^2} = -\gamma^2 \quad \rightarrow \quad Z = e^{\pm i \gamma z}$$

$$\frac{1}{Y} \frac{d^2 Y}{dy^2} = -\upsilon^2 \quad \rightarrow \quad Y = e^{\pm i \upsilon y} \quad (\mu^2 + \upsilon^2 + \gamma^2 = \lambda^2)$$

$$\frac{1}{X} \frac{d^2 X}{dx^2} = -\mu^2 \quad \rightarrow \quad X = e^{\pm i \mu x}$$

$$\Rightarrow \Psi(x, y, z) = \sum A e^{\pm i \mu x \pm i \upsilon y \pm i \gamma z}, \quad (\mu^2 + \upsilon^2 + \gamma^2 = \lambda^2)$$

# 柱座標系

$$\nabla^2 \Psi \equiv \frac{\partial^2 \Psi}{\partial r^2} + \frac{1}{r} \frac{\partial \Psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \Psi}{\partial \theta^2} + \frac{\partial^2 \Psi}{\partial z^2} + \lambda^2 \Psi = 0$$

$$\Psi \equiv R(r) \Theta(\theta) \Phi(z)$$

$$\Rightarrow \frac{1}{R} \frac{d^2 R}{dr^2} + \frac{1}{rR} \frac{dR}{dr} + \frac{1}{r^2 \Theta} \frac{d^2 \Theta}{d\theta^2} + \frac{1}{Z} \frac{d^2 Z}{dz^2} + \lambda^2 = 0$$

$$\left\{ \begin{array}{l} \frac{1}{Z} \frac{d^2 Z}{dz^2} = m^2 \quad \rightarrow \quad Z = e^{\pm mz} \\ \frac{1}{\Theta} \frac{d^2 \Theta}{d\theta^2} = -n^2 \quad \rightarrow \quad \Theta = e^{\pm in\theta} \end{array} \right.$$

$$\Rightarrow \frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} + \left( \lambda^2 + m^2 - \frac{n^2}{r^2} \right) R = 0 \quad \rightarrow \quad R = J_{\pm n}(\sqrt{\lambda^2 + m^2} r)$$

$$\Rightarrow \Psi \equiv R \Theta Z = \sum A J_{\pm n}(\sqrt{\lambda^2 + m^2} r) e^{\pm in\theta \pm mz}$$

# 球座標系

$$(\nabla^2 + \lambda^2)\Psi \equiv \frac{\partial^2 \Psi}{\partial r^2} + \frac{2}{r} \frac{\partial \Psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \Psi}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial \Psi}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \Psi}{\partial \phi^2} + \lambda^2 \Psi = 0$$

$$\Psi(r, \theta, \phi) \equiv R(r)\Theta(\theta)\Phi(\phi)$$

$$\Rightarrow \frac{1}{R} \left[ \frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} \right] + \frac{1}{r^2 \Theta} \left[ \frac{d^2 \Theta}{d\theta^2} + \cot \theta \frac{d\Theta}{d\theta} \right] + \frac{1}{r^2 \sin^2 \theta} \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} + \lambda^2 = 0$$

$$\Rightarrow \begin{cases} \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = -m^2 & \rightarrow \Phi = e^{im\phi} \\ \frac{1}{\Theta} \left[ \frac{d^2 \Theta}{d\theta^2} + \cot \theta \frac{d\Theta}{d\theta} \right] = \frac{m^2}{\sin^2 \theta} - n(n+1) & \rightarrow \Theta = CP_n^m(\cos \theta) + DQ_n^m(\cos \theta) \\ \frac{1}{R} \left[ \frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} \right] = \frac{n(n+1)}{r^2} - \lambda^2 & \rightarrow R = r^{-1/2} [AJ_{n+1/2}(\lambda r) + BY_{n+1/2}(\lambda r)] \end{cases}$$

$$\Rightarrow \Psi \equiv R\Theta\Phi = \sum r^{-1/2} [AJ_{n+1/2}(\lambda r) + BY_{n+1/2}(\lambda r)] [CP_n^m(\cos \theta) + DQ_n^m(\cos \theta)] e^{\pm im\phi}$$