

Introduction to Integral Equation

①

Let's start from a general second order ODE

$$\mathcal{L}y + f(x)y(x) = -R(x)$$

Here \mathcal{L} is a second order differential operator.

$$\Rightarrow \mathcal{L}y = -R(x) - f(x)y(x)$$

$$\Rightarrow y = - \int [R(x) + f(x)y(x)]g(x,s) ds$$

An integral equation

Green's function solution with the assumption that " $R(x) + f(x)y(x)$ " is the known non-homogeneous term.

Definitions (integral equation)

$$f(x) = \int_a^b k(x,t)\phi(t)dt, \text{ Fredholm equation of the first kind}$$

$$\phi(x) = f(x) + \lambda \int_a^b k(x,t)\phi(t)dt, \text{ Fredholm equation of the second kind}$$

$$f(x) = \int_a^x k(x,t)\phi(t)dt, \text{ Volterra equation of the 1st kind}$$

$$\phi(x) = f(x) + \int_a^x k(x,t)\phi(t)dt, \text{ Volterra equation of the 2nd kind}$$

Example: $\Sigma_s(E)\phi(E) = \int_E^{E_0} \frac{\Sigma_s(E')}{E'} \phi(E') dE' + \underbrace{S(E)}_{\text{SOURCE}}$

— Volterra eqn of 2nd kind

— Inhomogeneous

Show: $\frac{d^2 y}{dx^2} + A(x) \frac{dy}{dx} + B(x)y(x) = g(x)$ to be determined
 $y(0) = 0, y(a) = 0$
 can be converted to $y(x) = \int_0^a K(x, x') y(x') dx' - G(x)$

Let $\Sigma_s(E) \phi(E) = F(E)$

$$\Rightarrow F(E) = \int_E^{E_0} \frac{F(E')}{E'} dE' + S(E)$$

I.C. $F(E_0) = S(E_0)$

Sol:

$$\frac{d}{dE} \Rightarrow \frac{dF(E)}{dE} = \frac{dE_0}{dE} \frac{F(E_0)}{E_0} - \frac{dE}{dE} \frac{F(E)}{E} + \int_E^{E_0} \frac{d}{dE} \left(\frac{F(E')}{E'} \right) dE' + \frac{dS(E)}{dE}$$

$$\Rightarrow \frac{dF(E)}{dE} = - \frac{F(E)}{E_0} + \frac{dS(E)}{dE}$$

Note: Leibniz's rule

$$\frac{d}{dx} \int_{f(x)}^{g(x)} h(x, t) dt = g' h(x, g(x)) - f' h(x, f(x)) + \int_{f(x)}^{g(x)} \frac{\partial h}{\partial x} dt$$

$$\Rightarrow \frac{dF(E)}{dE} + \frac{1}{E} F(E) = \frac{dS(E)}{dE}$$

Integrating factor: $e^{\ln(\frac{1}{E})} = E^{-1}$

$$\Rightarrow \int_E^{E_0} d(EF(E)) = \int_E^{E_0} E' \frac{dS(E')}{dE'} dE' + \int_E^{E_0} E' dS(E')$$

$$\Rightarrow E_0 F(E_0) - EF(E) = E' S(E') \Big|_E^{E_0} - \int_E^{E_0} S(E') dE'$$

I.C. $F(E_0) = S(E_0) \Rightarrow E_0 F(E_0) = E_0 S(E_0)$

$$\Rightarrow EF(E) = ES(E) + \int_E^{E_0} S(E') dE'$$

$$\Rightarrow F(E) = S(E) + \frac{1}{E} \int_E^{E_0} S(E') dE'$$

$$\Rightarrow \phi(E) = \frac{S(E)}{\Sigma_s(E)} - \frac{1}{\Sigma_s(E)E} \int_E^{E_0} S(E') dE'$$

⊙ Numerical solution of integral equations

$$\phi(x) = \lambda \int_a^b k(x, x') \phi(x') dx' + H(x)$$

From numerical integration rules

$$I = \frac{h}{3} [f_0(x_0) + 4f_1(x_1) + f_2(x_2)] \quad \text{Simpson's rule}$$

or

$$I = \frac{h}{3} [f_0 + 4f_1 + 2f_2 + 4f_3 + \dots + f_N] \quad \text{Composite Simpson's rule}$$

$$\Rightarrow \phi(x) = \lambda \sum_{n=0}^3 w_n k(x, x_n) \phi(x_n) + H(x)$$

$$\Rightarrow \phi(x) - \lambda \sum_{n=0}^3 w_n k(x, x_n) \phi(x_n) = H(x)$$

$$\Rightarrow \left\{ \begin{aligned} \phi(x_0) - \lambda [w_0 k(x_0, x_0) \phi(x_0) + w_1 k(x_0, x_1) \phi(x_1) \\ + w_2 k(x_0, x_2) \phi(x_2) + w_3 k(x_0, x_3) \phi(x_3)] = H(x_0) \end{aligned} \right.$$

$$\left\{ \begin{aligned} \phi(x_1) - \lambda [\\] = H(x_1) \end{aligned} \right.$$

$$\left\{ \begin{aligned} \phi(x_2) - \lambda [\\] = H(x_2) \end{aligned} \right.$$

$$\left\{ \begin{aligned} \phi(x_3) - \lambda [\\] = H(x_3) \end{aligned} \right.$$

$$\Rightarrow A_{ij} \phi_j = H_i$$

$$A_{i,j} = \begin{cases} -\lambda w_j k(x_i, x_j), & i \neq j \\ 1 - \lambda w_j k(x_i, x_j), & i = j \end{cases}$$

$$\Rightarrow \text{Formal solution } \underline{\phi} = \underline{A}^{-1} \underline{H}$$

Fredholm eqn: A is a full matrix

Volterra eqn: A is a triangular matrix

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④ Neumann series techniques

$$\phi(x) = \lambda \int_a^b k(x, x') \phi(x') dx' + H(x)$$

$$\left. \begin{array}{l} \text{Neumann} \\ \text{series} \\ \text{solution} \end{array} \right\} \phi(x) = \sum_{l=0}^{\infty} \phi^l(x)$$

$$\phi^0(x) = H(x)$$

$$\phi^1(x) = \lambda \int_a^b k(x, x') \phi^0(x') dx'$$

⋮

$$\phi^n(x) = \lambda \int_a^b k(x, x') \phi^{n-1}(x') dx'$$

Convergence check

$$\frac{\sum_{l=0}^{\infty} (\phi^l(x) - \phi^{l-1}(x))}{\sum_{l=0}^{\infty} \phi^l(x)} < \varepsilon$$

→ If $\int_a^b k(x, x') dx' < 1$, convergence is guaranteed.

→ Banach Contraction Mapping Theorem
(Banach-Cacciopoli Fixed-Point Theorem)

Let \mathcal{F} be a closed subset of a Banach space,
and let $f: \mathcal{F} \rightarrow \mathcal{F}$ be a contraction. Then

$$\bar{x} = f(\bar{x})$$

has a unique solution \bar{x} in \mathcal{F} .